

# Dynamic Bayesian Network and Nonparametric Regression Model for Inferring Gene Networks

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## 1 Introduction

A Bayesian network is a powerful tool for modeling relations among a large number of random variables. Therefore the Bayesian network has received considerable attention from the studies of gene network estimation using microarray gene expression data. Imoto *et al.* [1, 2] proposed a Bayesian network and nonparametric regression model for capturing nonlinear relations between genes from the continuous gene expression data. However, a Bayesian network still has a problem that it cannot construct cyclic regulations, while real gene networks have cyclic regulations. For a solution of this problem, in this paper, we propose a dynamic Bayesian network and nonparametric regression model for estimating a gene network with cyclic regulations from time series microarray data. We also derive a criterion for selecting a network from Bayes approach. The effectiveness of our method is displayed through the analysis of the *Saccharomyces cerevisiae* gene expression data.

## 2 Method

Let  $X$  be an  $n \times p$  time series microarray data matrix, where  $n$  and  $p$  are the number of microarrays and genes, respectively. Under the first order Markov relation between the time points, the joint probability can then be decomposed as  $P(X_{11}, \dots, X_{np}) = P(\mathbf{X}_1)P(\mathbf{X}_2|\mathbf{X}_1) \times \dots \times P(\mathbf{X}_n|\mathbf{X}_{n-1})$ , where  $\mathbf{X}_i = (X_{i1}, \dots, X_{ip})^T$  is a random variable vector at time  $i$ . The conditional probability  $P(\mathbf{X}_i|\mathbf{X}_{i-1})$  can be decomposed as  $P(\mathbf{X}_i|\mathbf{X}_{i-1}) = P(X_{i1}|\mathbf{P}_{i-1,1}) \times \dots \times P(X_{ip}|\mathbf{P}_{i-1,p})$ , where  $\mathbf{P}_{i-1,j}$  denotes the parents of  $j$ th gene at time  $i-1$ .

Using the nonparametric regression in order to model the relationship between a gene and its parents, we define a dynamic Bayesian network and nonparametric regression model by the density,

$$f(x_{11}, \dots, x_{np}; \theta_G) = f_1(\mathbf{x}_1) \prod_{j=1}^p \left[ \prod_{i=2}^n \frac{1}{\sqrt{2\pi\sigma_j^2}} \exp \left\{ -\frac{(x_{ij} - \mu(\mathbf{p}_{i-1,j}))^2}{2\sigma_j^2} \right\} \right],$$

where  $\mathbf{p}_{i-1,j} = (p_{i-1,1}^{(j)}, \dots, p_{i-1,q_j}^{(j)})$  is a parents vector of  $j$ th gene, observed at time  $i-1$ .

When the network structure is given, we can construct a gene network by using the proposed model. However, the true gene network is still unknown, and we should guess the optimal network structure from the data. We derive a criterion for evaluating the network structure from Bayes approach. By using the Laplace approximation for integrals, the criterion, named  $\text{BNRC}_{\text{dynamic}}$  can be expressed as

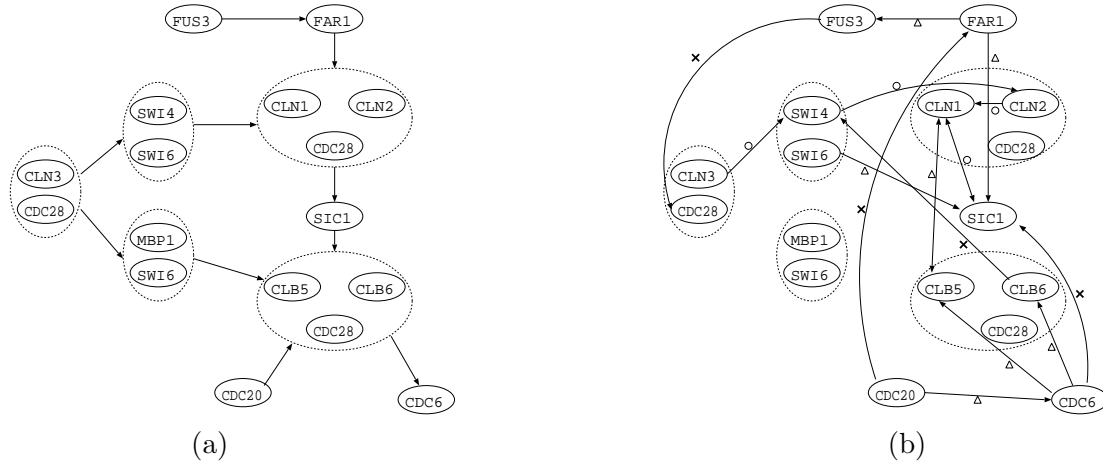


Figure 1: Yeast cell cycle pathway compiled by KEGG. (a) Target, (b) Estimate.

$$\begin{aligned} \text{BNRC}_{dynamic}(G) &= -2 \log \left\{ \pi_{prior}(G) \int f(x_{11}, \dots, x_{np}; \theta_G) \pi(\theta_G | \lambda) d\theta_G \right\} \\ &\approx -2 \log \pi_{prior}(G) - r \log(2\pi/n) + \log |J_\lambda(\hat{\theta}_G)| - 2n l_\lambda(\hat{\theta}_G | \mathbf{X}), \end{aligned}$$

where  $\pi(\theta_G | \lambda)$  and  $\pi_{prior}(G)$  are the prior distribution of the parameter  $\theta_G$  and the prior probability of the network  $G$ , respectively,  $\lambda$  is the hyper parameter vector,  $r$  is the dimension of  $\theta_G$ ,  $l_\lambda(\theta_G | \mathbf{X}) = \log f(x_{11}, \dots, x_{np}; \theta_G)/n + \log \pi(\theta_G | \lambda)/n$ ,  $J_\lambda(\theta_G) = -\partial^2 \{l_\lambda(\theta_G | \mathbf{X})\} / \partial \theta_G \partial \theta_G^T$  and  $\hat{\theta}_G$  is the mode of  $l_\lambda(\theta_G | \mathbf{X})$ . We can choose the optimal network such that the  $\text{BNRC}_{dynamic}$  is minimal.

### 3 Result

We apply the proposed method to the *Saccharomyces cerevisiae* cell cycle data collected by Spellman *et al.* [3]. The target network is a part of cell cycle pathway compiled by KEGG [4] and shown in Figure 1 (a). Figure 1 (b) is the estimated network based on the proposed method. In Figure 1 (b), we evaluate the estimated edges by three kinds of marks: Round is the correct edge, crisscross is the wrong edge and triangle represents the misdirection or skip.

### References

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